

### Problem Set 4

#### Question 1. *Logistic Equation:*

- (1) For this problem you will need the MATLAB ode solvers that we discussed in class: `ode1.m`, `ode2.m`, and `ode4.m`. Download `odex.zip` and unzip into a directory that you can find in MATLAB.
- (2) Create a MATLAB function to solve the Logistic Equation:

$$y' = ay - by^2$$

- (a) A function begins with the keyword `function`, then a comma separated list of outputs enclosed in brackets `[out1,out2,...,outN]`, followed by an equals sign, the name of the function and a comma separated list of inputs in parentheses `(in1,in2,...,inN)`.

```
function [out1,out2,...,outN]=function_name(in1,in2,...,inN)
```

Create a file called `logistic.m` using the command `edit logistic` in the same directory as you unzipped `odex.zip`.

- (b) Add the following to the file:

```
function [y,t,h]=logistic(a,b,t0,h,tf,y0,odex)
% logistic <Solves and plot the Logistic equation.>
% Usage:: [y,t,h]=logistic(a,b,t0,h,tf,y0,odex)
%
% Outputs:
% y is a column vector list containing the solution at the points t=(t0:h:tf)';
% t ??
% h is a handle to the plots h(1) numeric h(2) exact h(3) carrying capacity
%
% Inputs:
%
% a is the coefficient of the linear growth
% b ??
% ??
% ??
% ??
% ??
% odex is the name of the ode solver e.g., ode4
%
% revision history:
% 03/09/2026 Mark D. Shattuck <mds> logistic.m
%
%% Main
```

- (c) Fill in the list and descriptions of each input and output variable in place of the ??.

(d) Next add the definition of the logistic equation  $F(t, y)$  using an autonomous function:

$$y' = ay - by^2 = F(t, y)$$

For example, `F=@(t,y) a*y^2` will create a function  $F(t, y)$  that return  $a*y^2$ . Test this on the command line using the following:

```
>> a=4
a =
    4
>> F=@(t,y) a*y^2
F =
    @(t,y) a*y^2
>> F(0,3)
ans =
    36
>> a*3^2
ans =
    36
>>
```

Add a line defining `F` after the comment `%% Main`.

(e) Next we need to add the solution as we discussed in class:

```
[y,t]=odex(F,t0,h,tf,y0); % solve logistic equation using eg: odex=@ode4
```

(f) Next test the function:

```
>> [y,t]=logistic(2,3,0,1/2,6,1/300,@ode4);
>> plot(t,y)
```

These commands should create a plot showing the "S"-curve solution of the logistic equation. The final input into `logistic(...,@ode4)`, `@ode4`, is how to specify a function stored as a file like `ode4.m`. In `logistic.m` the last input `logistic(a,b,t0,h,tf,y0,odex)`, `odex`, will equal `@ode4`.

(g) Now we need to add plotting commands. Here is example code for the whole function including plotting:

```
function [y,t,h]=logistic(a,b,t0,h,tf,y0,odex)
% logistic <Solves and plot the Logistic equation.>
% Usage:: [y,t,h]=logistic(a,b,t0,h,tf,y0,odex)
%
% Outputs:
% y is a column vector list containing the solution at the points t=(t0:h:tf)';
% t ??
% h is a handle to the plots h(1) numeric h(2) exact h(3) carrying capacity
%
% Inputs:
%
% a is the coefficient of the linear growth
% b ??
```

```

% ??
% ??
% ??
% ??
% odex is the name of the ode solver e.g., ode4

% revision history:
% 03/09/2026 Mark D. Shattuck <mds> logistic.m

%% Main

F=@(t,y) ??;          % define logistic equation

[y,t]=odex(F,t0,h,tf,y0); % solve logistic equation
                               % using eg: odex=@ode4

%% Plotting

h=zeros(3); % handles to the 3 plots
            % handle can be used to change plots
            % set(h(1),'color','r') would change plot 1
            % color to red.

h(1)=plot(t,y,'o-'); % plot numeric solution y vs. t
set(h(1),'linewidth',2); % change linewidth
set(h(1),'markersize',12); % change markersize

hold all; % add new plots to current plot

% exact solution:
tt=t0+(0:100)/100*(tf-t0); % always use 100 points

d=??; % constant for exact soln
ye=a./(d*exp(-a*tt)+b);
h(2)=plot(tt,ye,'k','linewidth',2);

% plot of carrying capacity
h(3)=plot(tt,0*tt+a/b,'k--'); % plot y=a/b

% labels
set(gca,'fontsize',20);
xlabel('time');
ylabel('y(t)');

hold off; % clear before adding new plot

```

This code will solve and plot the odex solution, the exact solution, and the carrying capacity. It contains ?? from above. So be sure to replace those.

(h) To finish the exact solution section we need the null solution constant. In class we found that

$$(1) \quad y(t) = \frac{a}{de^{-at} + b}$$

solves the equation. Show that (1) solves the logistic equation.

(i) Find d for  $y(0) = y_0$  and add to the code.

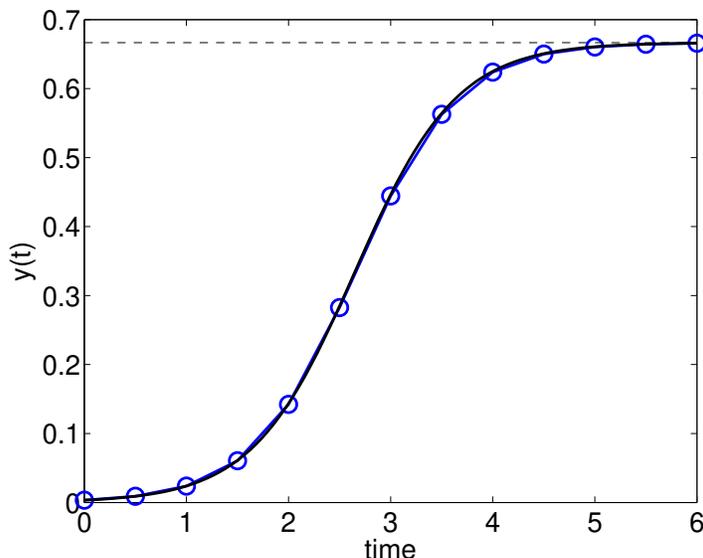


FIGURE 1. Result of `logistic(2,3,0,1/2,6,1/300,@ode4);`.

- (j) When everything is working the command `logistic(2,3,0,1/2,6,1/300,@ode4);` should produce the following plot.

$\LaTeX$  note: To add a MATLAB plot to a  $\LaTeX$  document use the MATLAB command

```
print -depsc2 log.eps
```

to create a color eps file. In  $\LaTeX$  use:

```
\begin{figure}
  \centering
  \includegraphics[width=0.5\linewidth]{log.eps}
  \caption{Result of \code{logistic(2,3,0,1/2,6,1/300,@ode4);}.}
  \label{fig:logsol}
\end{figure}
```

- (3) Use `logistic.m` to compare `ode4.m`, `ode2.m`, and `ode1.m`.

### Question 2. Variable Coefficients:

- (1) Solve the following equations for  $y(t)$ . You can leave your answer in terms of an integral if needed (but explain your reason).
  - (a)  $y' = 3t - 2ty$  given  $y(0) = 1$ .
  - (b)  $y' = 3t - 2ty$  given  $y(0) = 3/2$ .
  - (c)  $y' = e^{-t} - 2ty$  given  $y(0) = 1$ .
  - (d)  $y' = \sin(t)y$  given  $y(0) = 1$ .
  - (e)  $y' = \sin(t)y + t$  given  $y(0) = 1$ .
  - (f)  $y' = \log(t)y$  given  $y(0) = 1$ .
- (2) Use `ode4` to solve each equation above. Pick one and plot the exact solution and the solution from `ode4`.

**Question 3. General First-order Equations:**

- (1) Solve the following equations for  $y(t)$ . You can leave your answer in terms of an integral if needed (but explain your reason).
  - (a)  $y' = y^2 - y^3$  given  $y(0) = 1/3$ .
  - (b)  $y' = 2y - y^3$  given  $y(0) = 1/2$ .
  - (c)  $y' = \sqrt{y}$  given  $y(0) = 0$ .
  - (d)  $y' = \sin(t)y$  given  $y(0) = 1$ .
  - (e)  $y' = 3ty^2$  given  $y(0) = 1$ .
  - (f)  $y' = \frac{t}{\log(y)}$  given  $y(0) = 1$ .
- (2) Use `ode4` to solve each equation above. Pick one and plot the exact solution and the solution from `ode4`.

**Question 4. Stability:**

- (1) Find the fixed points and stability of Q3(1a)-(1c).
- (2) Choose one of Q3(1a)-(1c) and plot the exact solution, the `ode4` solution, and the fixed points. Add `ode4` solutions for several initial conditions in each stability region.

**Question 5. Second-order Equations:**

- (1) Solve the following equations for  $y(t)$ .
  - (a)  $y'' + y = 0$  given  $y(0) = 0, y'(0) = 1$ .
  - (b)  $y'' + 4y = \sin(3t)$  given  $y(0) = 1, y'(0) = 0$ .
  - (c)  $2y'' + y' + 3y = 0$  given  $y(0) = 0, y'(0) = 1$ .
- (2) For each equation find the characteristic equation and the roots.
- (3) Categorize each equation as over-damped, under-damped, or undamped.