

## Physics 37100 Advanced Physics Laboratory I

### Lab #5

(PART II: PID---The Controller)

- 1) Make a sketch using getPhoto() to control the LED using proportional control using  $V_{set}=V(128)$ . Here is an outline:
  - a. Set  $out=0$ ;
  - b. Loop for  $k=1$  to 100
  - c. Set analogWrite() to out
  - d. Wait 100ms.
  - e. Measure V using getPhoto
  - f. Serial.println V
  - g. Define err ie  $e=V_{set}-V$ ;
  - h. Define  $out=P*e$ ;
  - i. Make sure out is between [0 255].
  - j. Serial.println e and out
  - k. End loop
- 2) Find the largest value of  $P=P_{max}$  that does not causes the V to oscillate. How does it compare to your estimate from part I?
- 3) What is the value of the error for the largest P that will not oscillate?
- 4) Plot V and out verses step k from above for  $P_{max}$ ,  $P_{max}/2$ , and  $P_{max}/10$ .
- 5) Add Integral control. Initialize  $e_s$  to 0 before the loop and after line g above add  $e_s=e_s+e$ ; Then change line h to  $out=P*e+I*e_s$ .
- 6) Find values of  $P=P_0$  and  $I=I_0$  that give good control.
- 7) Plot V and out verses step k for  $(P_0,I_0)$ ,  $(P_0,I_0/10)$ ,  $(P_0/10,I_0)$ , and  $(P_0/10,I_0/10)$ . You may have to lengthen the k loop to see the full effects. Give a brief explanation of the plots.